

## ABSTRACT

The performance of a system for controlling vehicle-movement dynamics, which operates by means of the braking system and the drive train of a vehicle in order to prevent lateral breakaway of the vehicle, is improved yet further for the case in which oversteering of the vehicle is to be compensated. To this end it is proposed, according to the invention, that a braking moment be produced, by means of the braking system, on the front wheel on the outside of the bend, and an additional drive moment be built up, by means of the drive train, on the driven wheels.